Large Scale Machine Learning

European Summer School in Financial Mathematics, Le Mans

S. Gaïffas



Presentation

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Big Data in More Hands

By QUENTIN HARDY

Business people, Big Data is coming for you.

Software that captures lots of data and uses it to make predictions has mostly been the province of engineers skilled in arcane databases and statisticians capable of developing complex algorithms. As the business gets bigger, however, software makers are domesticating their products in the hope they will prove attractive to a broader population.

Cloudera, which offers a popular version of the open source database called Hadoop, released software on Wednesday that makes it possible to run queries from a more mainstream SQL programming language interface. SQL, thanks to its adoption by Oracle, Microsoft and others, is known to millions of business analysts.

"This enables us to talk to a whole other class of customer," said Mike Olson, the chief executive of Cloudera. "The knock against Hadoop was that it is too complex."

There is a reason for that. Hadoop is one of several so-called unstructured databases that were created at Yahoo and Google, after those two companies found they had previously unimaginable amounts of data about activities like people's Web-surfing habits. Put into databases designed to handle this unstructured behavior, then analyzed, this information was

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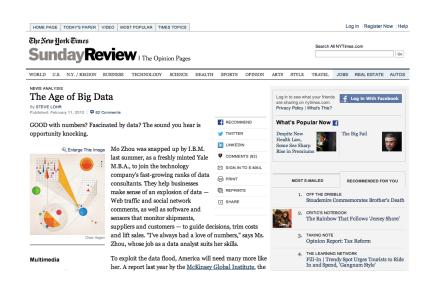
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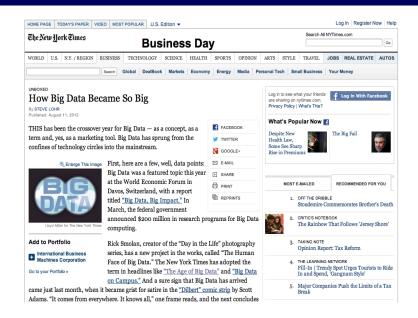
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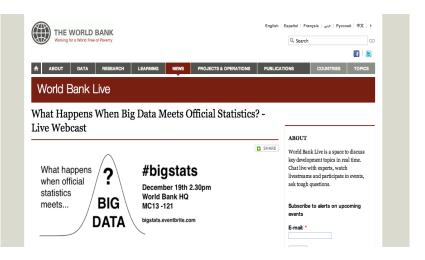
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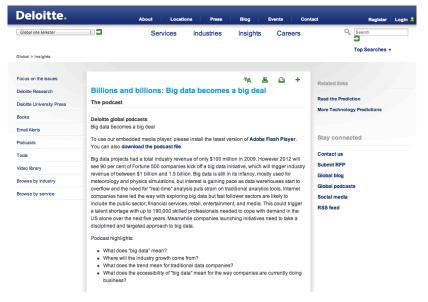
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CriteoLabs : soirée d'inauguration

Criteo inaugure à Paris l'un des premiers centres de R&D en publicité prédictive d'Europe

- > Fleur Pellerin, Ministre déléquée chargée des PME, de l'innovation et de l'Economie Numérique, apporte son soutien à cette entreprise innovante du secteur numérique, véritable « success story » à la française.
- Criteo inaugure CriteoLabs, son nouveau centre de R&D de 10.000 m2 au cœur de Paris.
- > Avec à terme 300 ingénieurs, ce site est déjà l'un des premiers centres européens de R&D en algorithmes appliqués à la publicité en ligne. Pour accompagner sa forte croissance. Criteo recrute cette année 250 nouveaux collaborateurs.









Criteo inaugure à Paris l'un des plus gros pôles européens de R&D dédiés à la publicité prédictive, CriteoLabs, Sur 10.000 m2, ce nouveau centre a vocation à accueillir 300 ingénieurs et à permettre ainsi à Criteo de garantir son avancée technologique sur ses 30 marchés d'exportation, des Etats-Unis, à l'Europe, en passant par l'Asie. Cette année, l'entreprise compte ainsi recruter 250 nouveaux collaborateurs, dont une centaine d'ingénieurs,

Ce nouveau siège, que Criteo a choisi délibérément de situer à Paris, vient ponctuer un développement continu, qui a permis à l'entreprise d'atteindre des résultats remarquables, 3 ans seulement après son lancement commercial ;

- > 600 salariés présents dans 15 bureaux dans le monde
- > 2 000 annonceurs, parmi les plus importants e-commercants mondiaux tels que Dell, Macy's, John Lewis, Marks
- & Spencers, Zalando, La Redoute, Les 3 Suisses, etc. 4 000 éditeurs
 - > Plus de 200 millions de dollars de CA en 2011

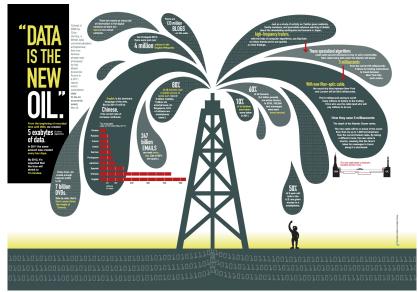




Arrivée de Fleur Pellerin



Data is the new oil?



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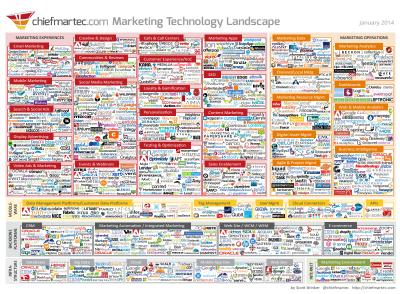
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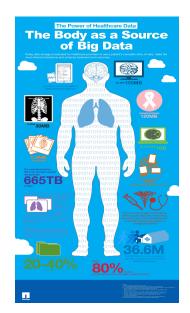
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The Predictive Policing Company.

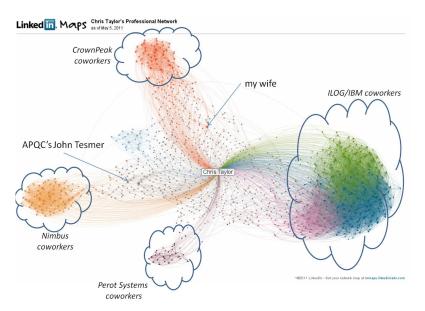
PredPol's cloud-based software enables law enforcement agencies to better prevent crime in their communities by generating predictions on the places and times that future crimes are most likely to occur.

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Smart city

human use goes to urban cities.

Smarter Cities: Turning Big Data Into Insight City Planning and Operations **Transportation Analytics** \$1 Trillion 50 Hours global annual savings could be attained by of traffic delays per year are incurred. optimizing public infrastructure. on average, by travelers. Source: McKinsev \$57 Trillion 30 Billion in infrastructure investments will be people all over the world travel needed between 2013-2030. approximately 30 billion miles per Source: McKinsev year, By 2050, that figure will grow to over 150 billion miles Cloud is driving cities in their digital transformation. Water Management Open Cloud 60% \$6 Billion of water allocated for domestic has been invested by IBM in more than \$14 Billion 37.000

IBM Intelligent Operations software is designed with cities, for cities, to provide the tools to monitor, visualize and analyze vital city services such as water and wastewater systems, transportation, infrastructure planning, permit management and emergency response.

in potable water is lost every year because

of leaks, theft and unbilled usage,

Source: World Bank

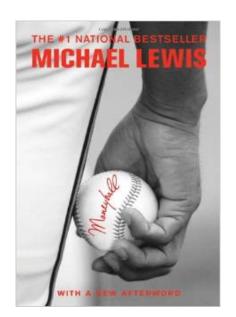


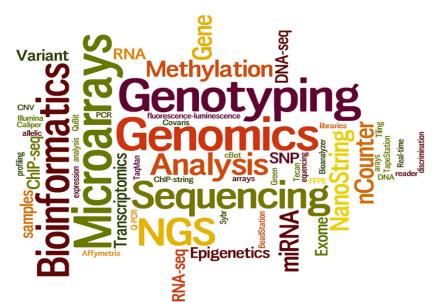
a dozen acquisitions to accelerate its

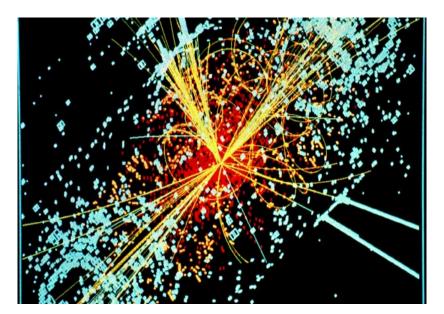
cloud initiatives.

cloud experts support IBM's

industry team alone.







Wikipedia I

Big data

From Wikipedia, the free encyclopedia

This article is about large collections of data. For the band, see Big Data (band).

Big data [12] is the term for a collection of data sets so large and complex that it becomes difficult to process using on-hand database management tools or traditional data processing applications. The challenges include capture, curation, storage, [3] easen't, sharing, transfer, analysis of a single large sof related data, as compared to separate smaller sets with the same total amount of data, allowing correlations to be found to "spot business trends, determine quality of research, prevent diseases, link least citations, combat crime, and determine real-time read-way traffic conditions.* [5] [17] [17]

As of 2012, limits on the size of data sets that are feasible to process in a reasonable amount of time were on the order of exabytes of data. Significant concurring initiations due to large data sets in many areas, including meteorology, genomics, Significant complex physics simulations, I¹⁰ and biological and environmental research. I¹¹ The initiations also affect internet search, finance and business information, but sets grow in size in part because they are increasingly being gathered by ubcultous information-sensing mobile devices, serial sensory technologies (remote sensing), software logs, cameras, microphones, radio-frequency definitions reades, and witeless sensor networks (I²²). The world's serionological per-capital capacity to store information has roughly doubled every 40 months since the 1980/s¹¹ as of 2012, every day 2.5 exabytes (2.5×10¹⁵) of data were created. I¹⁰ The challenge for large enterprises is determining who soluted work to data intakes that straded the entire conscription. I¹⁰

Big data is difficult to work with using most relational database management systems and desktop statistics and visualization packages, requiring instead "massively parallel software running on tens, hundreds, or even thousands of servers". If what is considered "tip data" varies depending on the capabilities of the oppications that are traditionally used to process and analyze the data set in its domain. For some organization, facing hundreds of glaphyses of data for the first time may trigger a need to reconsider data management options. For others, it may take tens or hundreds of prinarybes before data size becomes a significant consideration, if \$\frac{1}{2}\$!



A visualization created by IBM of Wikipedia edits. At multiple terabytes in size, the text and images of Wikipedia are a classic example of big data.

Wikipedia II

- Big data is an all-encompassing term for any collection of data sets so large and complex that it becomes difficult to process using traditional data processing applications.
- **Data science** is the study of the generalizable extraction of knowledge from data, yet the key word is science.
- **Statistics** is the study of the collection, analysis, interpretation, presentation and organization of data.

Big data

- Capacity to store information has doubled every 40 months since the 1980s
- In 2012, 2.5 exabytes (2.5×10^{18}) created per day
- Big internet companies such as Google, Amazon, Facebook, but also industries from pharmaceuticals, insurance, banks, telecoms, personalized medicine, marketing, bioinformatics

A new Context

Data everywhere

- Huge volume,
- Huge variety...

Affordable computation units

- Cloud computing
- Graphical Processor Units (GPU)...
- Growing academic and industrial interest!

Big Data is (quite) Easy

Example of off the shelves solution





```
f run(params: Params) {
val conf = new SparkConf()
    .setAppName(s"BinaryClassification with $params")
val sc = new SparkContext(conf)
Logger.getRootLogger.setLevel(Level.WARN)
val examples = MLUtils.loadLibSVMFile(sc, params.input).cache()
val splits = examples.randomSplit(Array(0.8, 0.2))
val training = splits(0).cache()
val test = splits(1).cache()
val numTraining = training.count()
val numTest = test.count()
println(s"Training: $numTraining, test: $numTest.")
examples.unpersist(blocking = false)
val updater = params.regType match {
  case L1 => new L1Updater()
  case L2 => new SquaredL2Updater()
val algorithm = new LogisticRegressionWithSGD()
    algorithm.optimizer
      .setNumIterations(params.numIterations)
      .setStepSize(params.stepSize)
      .setUpdater(updater)
       .setRegParam(params.regParam)
val model = algorithm.run(training).clearThreshold()
val prediction = model.predict(test.map(..features))
val predictionAndLabel = prediction.zip(test.map( .label))
val netrics = new BinaryClassificationMetrics(predictionAndLabel)
val myMetrics = new MyBinaryClassificationMetrics(predictionAndLabel)
println(s"Empirical CrossEntropy = ${mvMetrics.crossEntropy()}.")
println(s"Test areaUnderPR = ${metrics.areaUnderPR()}.")
println(s"Test areaUnderROC = ${metrics.areaUnderROC()}.")
sc.stop()
```

Big Data is (quite) Easy

Example of off the shelves solution

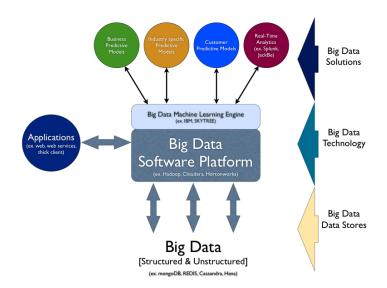




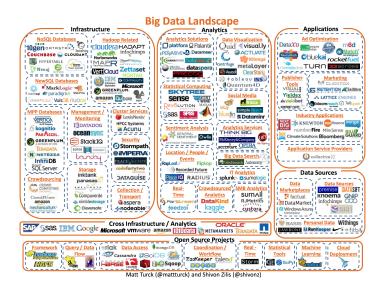
```
export AWS_ACCESS_KEY_ID=<your-access-keyid>
export AWS_SECRET_ACCESS_KEY=<your-access-key-secret>
cellule/spark/ec2/sparl-ec2 -i cellule.pem -k cellule -s <number of machines> launch <cluster-name>
ssh -i cellule.pem root@<your-cluster-master-dns>
spark-ec2/copy-dir ephemeral-hdfs/conf
ephemeral-hdfs/bin/hadoop distcp s3n://celluledecalcul/dataset/raw/train.csv /data/train.csv
scp -i cellule.pem cellule/challenge/target/scala-2.10/target/scala-2.10/challenges 2.10-0.0.jar
cellule/spark/bin/spark-submit \
        --class fr.cc.challenge.Preprocess \
        challenges_2.10-0.0.jar \
        /data/train.csv \
        /data/train2.csv
cellule/spark/bin/spark-submit \
       --class fr.cc.sparktest.LogisticRegression \
      challenges_2.10-0.0.jar \
      /data/train2.csv
```

⇒ Logistic regression for arbitrary large dataset!

A Complex Ecosystem! I



A Complex Ecosystem! II



Data science or statistics? I

A vocabulary problem:

data scientist or statistician?

statistics or data science?

Data science or statistics? II

A possible answer:

Data science or statistics? III



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Supervised learning

Setting

- Data $x_i \in \mathcal{X}$, $y_i \in \mathcal{Y}$ for i = 1, ..., n
- x_i is an input and y_i is an output
- x_i are called **features** and $x_i \in \mathcal{X} = \mathbb{R}^d$
- y_i are called **labels**

$$\mathcal{Y}=\{-1,1\}$$
 or $\mathcal{Y}=\{0,1\}$ for binary classification $\mathcal{Y}=\{1,\ldots,K\}$ for multiclass classification $\mathcal{Y}=\mathbb{R}$ for regression

- Usually, assume (x_i, y_i) are i.i.d
- Goal: given x, predict y.

Supervised learning

- High-dimension: d is large, say $d \ge 10^4$
- Big data: n is large, say $n \ge 10^6$

Scenarios where:

- d is large, n is small: computational biology
- d is small, n is large: marketing
- *d* is large, *n* is large: web-advertisement, ad display

What to do

Minimize with respect to $f: \mathbb{R}^d \to \mathbb{R}$

$$R_n(f) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, f(x_i))$$

where

- ℓ is a **loss** function. $\ell(y_i, f(x_i))$ small means y_i is close to $f(x_i)$
- $R_n(f)$ is called **goodness-of-fit** or **empirical risk**

Computation of f is called **training** or **estimation** step

- When d is large, impossible to fit a complex functions f on the data
- When n is large, training is too time-consuming for a complex function f

Hence:

• Choose a **linear** function f:

$$f(x) = \langle x, \theta \rangle = \sum_{j=1}^{d} x_j \theta_j,$$

for some parameter vector $\theta \in \mathbb{R}^d$ to be trained

Remark: linear with respect to x_i , but **you** can choose the x_i based on the data. Hence, not linear w.r.t the original features: "feature engineering"

• Least-squares loss (linear regression): $\ell(y,z) = \frac{1}{2}(y-z)^2$ for $y \in \mathbb{R}$, namely

$$R_n(\theta) = \frac{1}{2n} \sum_{i=1}^n (y_i - \langle x_i, \theta \rangle)^2 = \frac{1}{2n} ||Y - X\theta||_2^2$$

where
$$X = [X_1, \cdots, X_n]^{\top} \in \mathbb{R}^{n \times d}$$
 and $y = [y_1, \cdots, y_n] \in \mathbb{R}^d$

• Logistic regression loss (logit, log-linear regression): $\ell(y,z) = \log(1+e^{-yz})$ for $y \in \{-1,1\}$, namely

$$R_n(\theta) = \frac{1}{n} \sum_{i=1}^n \log(1 + e^{-y_i \langle x_i, \theta \rangle})$$

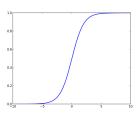


Binary classification: label $y \in \{0,1\}$. Assume that

$$\mathbb{P}(Y = y | X = x) = \text{Bernoulli}(\sigma_{\theta}(x))$$

with $\sigma_{\theta}(x) = \sigma(\langle \theta, x \rangle)$ where σ is the **sigmoid** function

$$\sigma(z)=\frac{1}{1+e^{-z}}.$$



Binary classification: label $y \in \{0,1\}$. Assume that

$$\mathbb{P}(Y = y | X = x) = \text{Bernoulli}(\sigma_{\theta}(x))$$

with $\sigma_{\theta}(x) = \sigma(\langle \theta, x \rangle)$ where σ is the **sigmoid** function

$$\sigma(z)=\frac{1}{1+e^{-z}}.$$

Hence for $y \in \{0, 1\}$:

$$\mathbb{P}(Y = y | X = x) = \sigma_{\theta}(x)^{y} (1 - \sigma_{\theta}(x))^{1-y} = \sigma_{\theta}(x)^{y} \sigma_{\theta}(-x)^{1-y}$$

and the log-likelihood is given by (if we replace label 0 by -1 for convenience)

$$\sum_{i=1}^n \log \mathbb{P}[Y = y_i | X = x_i] = -\sum_{i=1}^n \log(1 + e^{-y_i \langle x_i, \theta \rangle})$$

Goodness of fit = - log-likelihood, so this leads to

$$R_n(\theta) = \frac{1}{n} \sum_{i=1}^n \log(1 + e^{-y_i \langle x_i, \theta \rangle})$$

Equivalent to assuming that the log-odd ratio is linear:

$$\log \left(\frac{\mathbb{P}[Y=1|X=x]}{\mathbb{P}[Y=0|X=x]} \right) = \langle x, \theta \rangle$$

This leads to a **linear** separation between the 1s and 0s. Logistic regression is a **linear** classifier

Now I've trained a logistic classifier: I have an estimation $\hat{\theta}$ of the parameters based on data $(x_1, y_1), \dots, (x_n, y_n)$

I have a new point x_{n+1} but no label y_{n+1} for him. I want to have a prediction $\hat{y}_{n+1} \in \{-1,1\}$ of its label

How do I proceed?

• I compute probability scores of 1 and -1:

$$\hat{
ho}_{n+1}^{(1)} = rac{1}{1 + e^{-\langle \mathsf{X}_{n+1}, \hat{ heta}
angle}} \quad ext{and} \quad \hat{
ho}_{n+1}^{(-1)} = 1 - \hat{
ho}_{n+1}^{(1)}$$

 Now I predict the label using the MAP rule (Maximum A Posteriori)

$$\hat{y}_{n+1} = egin{cases} 1 & ext{if } \hat{p}_{n+1}^{(1)} \geq t \ -1 & ext{otherwise} \end{cases}$$

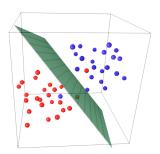
for a threshold $t\in (0,1)$ (usually t=1/2)

Remark:

$$\hat{\rho}_{n+1}^{(1)} \geq t \Leftrightarrow \langle x_{n+1}, \hat{\theta} \rangle \geq \log \left(\frac{t}{1-t} \right) \quad \left(\langle x_{n+1}, \hat{\theta} \rangle \geq 0 \text{ if } t = 1/2 \right)$$

This means that the logistic classifier separates data points into 1 and -1 with a hyperplane

We say that it is a linear classifier



Training the model: compute

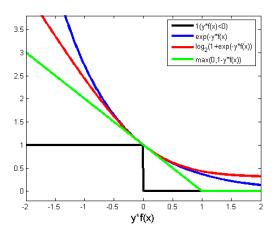
$$\hat{\theta} \in \operatorname*{argmin}_{\theta \in \mathbb{R}^d} R_n(\theta)$$

where

$$R_n(\theta) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, \langle x_i, \theta \rangle).$$

Classical losses

- $\ell(y,z) = \frac{1}{2}(y-z)^2$: least-squares loss, linear regression (label $y \in \mathbb{R}$)
- $\ell(y,z) = (1-yz)_+$ hinge loss, or SVM loss (binary classification, label $y \in \{-1,1\}$)
- $\ell(y,z) = \log(1+e^{-yz})$ logistic loss (binary classification, label $y \in \{-1,1\}$)



$$\ell_{ ext{least-sq}}(y,z) = rac{1}{2}(y-z)^2 \quad \ell_{ ext{hinge}}(y,z) = (1-yz)_+$$
 $\ell_{ ext{logistic}}(y,z) = \log(1+e^{-yz})$

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You should never actually fit a model by minimizing only

$$\hat{\theta}_n \in \underset{\theta \in \mathbb{R}^d}{\operatorname{argmin}} \frac{1}{n} \sum_{i=1}^n \ell(y_i, \langle x_i, \theta \rangle).$$

You should minimize instead

$$\hat{ heta}_n \in \operatorname*{argmin}_{ heta \in \mathbb{R}^d} \left\{ rac{1}{n} \sum_{i=1}^n \ell(y_i, \langle x_i, heta
angle) + \lambda \operatorname{pen}(heta)
ight\}$$

where

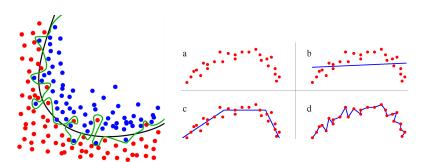
- pen is a **penalization** function, that encodes a prior assumption on θ . It forbids θ to be "too complex"
- $\lambda > 0$ is a **tuning** or **smoothing** parameter, that **balances** goodness-of-fit and penalization

Penalization - Introduction

Why using penalization?

$$\hat{\theta} \in \operatorname*{argmin}_{\theta \in \mathbb{R}^d} \left\{ \frac{1}{n} \sum_{i=1}^n \ell(y_i, \langle x_i, \theta \rangle) + \lambda \operatorname{pen}(\theta) \right\}$$

Penalization, for a well-chosen $\lambda > 0$, allows to avoid **overfitting**



Penalization – Ridge

Most classical penalization is the Ridge penalization

$$\mathsf{pen}(heta) = \| heta\|_2^2 = \sum_{j=1}^d heta_j^2.$$

It penalizes the energy of θ , measured by squared ℓ_2 -norm

Sparsity inducing penalization.

- ullet It would be nice to find a model where $\hat{ heta}_j = 0$ for many coordinates j
- few features are useful for prediction, the model is simpler, with a smaller dimension
- We say that $\hat{\theta}$ is **sparse**
- How to do it?

Penalization – Sparsity

It is tempting to use

$$\hat{\theta} \in \underset{\theta \in \mathbb{R}^d}{\operatorname{argmin}} \Big\{ \frac{1}{n} \sum_{i=1}^n \ell(y_i, \langle x_i, \theta \rangle) + \lambda \|\theta\|_0 \Big\},$$

where

$$\|\theta\|_0 = \#\{j : \theta_i \neq 0\}.$$

But, to do it exactly, you need to try **all** possible subsets of non-zero coordinates of θ : 2^d possibilities. Impossible!

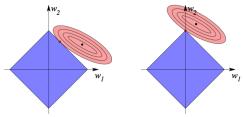
Penalization - Lasso

A solution: **Lasso** penalization (least absolute shrinkage and selection operator)

$$\mathsf{pen}(heta) = \| heta\|_1 = \sum_{j=1}^d | heta_j|.$$

This is penalization based on the ℓ_1 -norm $\|\cdot\|_1$.

- In a noiseless setting, in a certain regime, ℓ_1 -minimization gives the "same solution" as $\|\cdot\|_0$
- Why do ℓ_1 -penalization leads to sparsity?



Why ℓ_2 (ridge) does not induce sparsity?

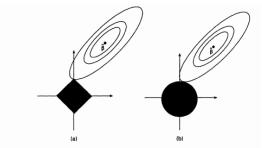


Fig. 2. Estimation picture for (a) the lasso and (b) ridge regression

Hence, a minimizer

$$\hat{\theta} \in \operatorname*{argmin}_{\theta \in \mathbb{R}^d} \left\{ \frac{1}{n} \sum_{i=1}^n \ell(y_i, \langle x_i, \theta \rangle) + \lambda \|\theta\|_1 \right\}$$

is typically sparse $(\hat{\theta}_j = 0 \text{ for many } j)$.

- ullet for λ large (larger than some constant) $\hat{ heta}_j = 0$ for all j
- ullet for $\lambda=0$ then there is no penalization
- Between the two, the "sparsity" depends on the value of λ : once again, it is a regularization or penalization parameter

Penalization – Lasso

For the least squares loss

$$\hat{\theta} \in \operatorname*{argmin}_{\theta \in \mathbb{R}^d} \left\{ \frac{1}{2n} \|Y - X\theta\|_2^2 + \frac{\lambda}{2} \|\theta\|_2^2 \right\}$$

is called ridge linear regression, and

$$\hat{\theta} \in \operatorname*{argmin}_{\theta \in \mathbb{R}^d} \left\{ \frac{1}{2n} \| Y - X \theta \|_2^2 + \lambda \| \theta \|_1 \right\}$$

is called **Lasso** linear regression.

Penalization - Lasso

Consider the minimization problem

$$\min_{a \in \mathbb{R}} \frac{1}{2} (a - b)^2 + \lambda |a|$$

for $\lambda > 0$ and $b \in \mathbb{R}$

- Derivative at 0_+ : $d_+ = \lambda b$
- Derivative at 0_- : $d_- = -\lambda b$

Let a_* be the solution

- $a_*=0$ iff $d_+\geq 0$ and $d_-\leq 0$, namely $|b|\leq \lambda$
- $a_* \geq 0$ iff $d_+ \leq 0$, namely $b \geq \lambda$ and $a_* = b \lambda$
- $a_* \leq 0$ iff $d_- \geq 0$, namely $b \leq -\lambda$ and $a_* = b + \lambda$

Hence

$$a_* = \operatorname{sign}(b)(|b| - \lambda)_+$$

where $a_+ = \max(0, a)$



Penalization - Lasso

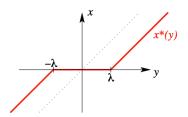
As a consequence, we have

$$a_* = \operatorname*{argmin}_{a \in \mathbb{R}^d} rac{1}{2} \|a - b\|_2^2 + \lambda \|a\|_1 = \mathcal{S}_{\lambda}(b)$$

where

$$S_{\lambda}(b) = \operatorname{sign}(b) \odot (|b| - \lambda)_{+}$$

is the **soft-thresholding** operator



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Proximal operator

• For any g convex [lower semi-continuous] and any $y \in \mathbb{R}^d$, we define the **proximal operator**

$$\operatorname{prox}_{g}(y) = \operatorname*{argmin}_{x \in \mathbb{R}^{d}} \left\{ \frac{1}{2} \|x - y\|_{2}^{2} + g(x) \right\}$$

(strongly convex problem ⇒ unique minimum)

ullet We already proved that soft-thresholding is the proximal operator of the ℓ_1 -norm

$$\mathsf{prox}_{\lambda\|\cdot\|_1}(y) = \mathcal{S}_{\lambda}(y) = \mathsf{sign}(y) \odot (|y| - \lambda) +$$

Proximal operators and proximal algorithms are now **fundamental tools** for optimization in machine learning

Examples of proximal operators

- g(x) = c for a constant c, $prox_g = Id$
- If C convex set, and

$$g(x) = \delta_C(x) = \begin{cases} 0 & \text{if } x \in C \\ +\infty & \text{if } x \notin C \end{cases}$$

then

$$prox_g = proj_C = projection onto C.$$

• If $g(x) = \langle b, x \rangle + c$, then

$$\operatorname{prox}_{\lambda g}(x) = x - \lambda b$$

• If $g(x) = \frac{1}{2}x^{\top}Ax + \langle b, x \rangle + c$ with A symetric positive, then

$$\operatorname{prox}_{\lambda g}(x) = (I + \lambda A)^{-1}(x - \lambda b)$$



Examples of proximal operators

• If $g(x) = \frac{1}{2} ||x||_2^2$ then

$$\operatorname{prox}_{\lambda g}(x) = \frac{1}{1+\lambda} x = \operatorname{shrinkage}$$
 operator

• If $g(x) = -\log x$ then

$$\operatorname{prox}_{\lambda g}(x) = \frac{x + \sqrt{x^2 + 4\lambda}}{2}$$

• If $g(x) = ||x||_2$ then

$$\operatorname{prox}_{\lambda g}(x) = \left(1 - \frac{\lambda}{\|x\|_2}\right)_+ x,$$

the block soft-thresholding operator



Examples of proximal operators

• If $g(x) = ||x||_1 + \frac{\gamma}{2}||x||_2^2$ (elastic-net) where $\gamma > 0$, then

$$\operatorname{prox}_{\lambda g}(x) = \frac{1}{1 + \lambda \gamma} \operatorname{prox}_{\lambda \| \cdot \|_1}(x)$$

• If $g(x) = \sum_{g \in G} \|x_g\|_2$ where G partition of $\{1, \dots, d\}$,

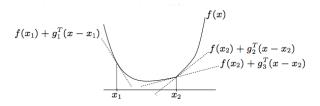
$$(\operatorname{prox}_{\lambda g}(x))_g = \left(1 - \frac{\lambda}{\|x_g\|_2}\right)_+ x_g,$$

for $g \in G$. Block soft-thresholding, used for group-Lasso



The **subdifferential** of $f \in \Gamma^0$ at x is the set

$$\partial f(x) = \left\{ g \in \mathbb{R}^d : f(y) \ge \langle g, y - x \rangle + f(x) \text{ for all } y \in \mathbb{R}^d \right\}$$



- Each element is called a subgradient
- Optimality criterion

$$0 \in \partial f(x)$$
 iff $f(x) \le f(y) \forall y$

- If f is differentiable at x, then $\partial f(x) = {\nabla f(x)}$
- Example: $\partial |0| = [-1, 1]$



$$f: \mathbb{R}^d \to [-\infty, +\infty]$$
 is

• f is L-smooth if it is continuously differentiable and if

$$\|\nabla f(x) - \nabla f(y)\|_2 \le L\|x - y\|_2$$
 for any $x, y \in \mathbb{R}^d$.

Equivalent to $H_f(x) \leq LI_d$ for all x, where $H_f(x)$ Hessian at x when twice continuously differentiable [i.e. $LI_d - H_f(x)$ positive semi-definite]

• f is μ -strongly convex if $f(\cdot) - \frac{\mu}{2} \|\cdot\|_2^2$ is convex. Equivalent to

$$f(y) \ge f(x) + \langle g, y - x \rangle + \frac{\mu}{2} ||y - x||_2^2$$

for $g \in \partial f(x)$. Equivalent to $H_f(x) \succeq \mu I_d$ when twice differentiable.



Optimality criterion

Optimality criterion: $\theta_* \in \operatorname{argmin}_{\theta \in \mathbb{R}^d} \{ f(\theta) + g(\theta) \}$ iff

$$-\nabla f(\theta_*) \in \partial g(\theta_*)$$

namely

$$-\frac{1}{\lambda}\nabla R_n(\theta_*)\in\partial g(\theta_*)$$

For the Lasso

$$\hat{\theta} \in \operatorname*{argmin}_{\theta \in \mathbb{R}^d} \left\{ \frac{1}{2n} \|Y - X\theta\|_2^2 + \lambda \|\theta\|_1 \right\}$$

this optimality criterion is

$$\begin{cases} \frac{1}{n}|X_j^\top(Y-X\hat{\theta})| \leq \lambda & \text{if } \hat{\theta}_j = 0 \\ \frac{1}{n}X_j^\top(Y-X\hat{\theta}) = \lambda \operatorname{sign}(\hat{\theta}_j) & \text{if } \hat{\theta}_j \neq 0 \end{cases}$$

for any j = 1, ..., d, where X_i is the j-th conumn of X.



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The general problem we want to solve

How to solve

$$\hat{\theta} \in \operatorname*{argmin}_{\theta \in \mathbb{R}^d} \left\{ \frac{1}{n} \sum_{i=1}^n \ell(y_i, \langle x_i, \theta \rangle) + \lambda \operatorname{pen}(\theta) \right\} \quad ???$$

Put for short

$$f(\theta) = \frac{1}{n} \sum_{i=1}^{n} \ell(y_i, \langle x_i, \theta \rangle)$$
 and $g(\theta) = \lambda \operatorname{pen}(\theta)$

Assume that

- f is convex and L-smooth
- g is convex and continuous, but possibly non-smooth (for instance ℓ_1 penalization)
- g is **prox-capable**: not hard to compute its proximal operator

Smoothness of f:

• Least-squares:

$$\nabla f(\theta) = \frac{1}{n} X^{\top} (X\theta - Y), \quad L = \frac{\|X^{\top} X\|_{\text{op}}}{n}$$

Logistic loss:

$$\nabla f(\theta) = -\frac{1}{n} \sum_{i=1}^{n} \frac{y_i}{1 + e^{y_i \langle x_i, \theta \rangle}} x_i, \quad L = \frac{\max_{i=1, \dots, n} \|X_i\|_2^2}{4n}$$

Prox-capability of g:

• we gave the explicit prox for many penalizations above



Gradient descent

Now how do I minimize f + g?

• Key point: the **descent lemma**. If f convex and L-smooth, then for any $L' \geq L$:

$$f(\theta') \le f(\theta) + \langle \nabla f(\theta), \theta' - \theta \rangle + \frac{L'}{2} \|\theta' - \theta\|_2^2$$

for any $\theta, \theta' \in \mathbb{R}^d$

• At iteration k, the current point is θ^k . I use the descent lemma:

$$f(\theta) \le f(\theta^k) + \langle \nabla f(\theta^k), \theta - \theta^k \rangle + \frac{L'}{2} \|\theta - \theta^k\|_2^2.$$



Remark that

$$\begin{aligned} & \underset{\theta \in \mathbb{R}^d}{\operatorname{argmin}} \left\{ f(\theta^k) + \langle \nabla f(\theta^k), \theta - \theta^k \rangle + \frac{L'}{2} \|\theta - \theta^k\|_2^2 \right\} \\ & = \underset{\theta \in \mathbb{R}^d}{\operatorname{argmin}} \left\| \theta - \left(\theta^k - \frac{1}{L'} \nabla f(\theta^k) \right) \right\|_2^2 \end{aligned}$$

• Hence, choose

$$\theta^{k+1} = \theta^k - \frac{1}{L'} \nabla f(\theta^k)$$

This is the basic **gradient descent** algorithm [cf previous lecture]

- Gradient descent is based on a majoration-minimization principle, with a quadratic majorant given by the descent lemma
- But we forgot about g...

Let's put back g:

$$f(\theta) + g(\theta) \le f(\theta^k) + \langle \nabla f(\theta^k), \theta - \theta^k \rangle + \frac{L'}{2} \|\theta - \theta^k\|_2^2 + g(\theta)$$

and again

$$\begin{aligned} & \underset{\theta \in \mathbb{R}^d}{\operatorname{argmin}} \left\{ f(\theta^k) + \langle \nabla f(\theta^k), \theta - \theta^k \rangle + \frac{L'}{2} \|\theta - \theta^k\|_2^2 + g(\theta) \right\} \\ & = \underset{\theta \in \mathbb{R}^d}{\operatorname{argmin}} \left\{ \frac{L'}{2} \left\| \theta - \left(\theta^k - \frac{1}{L'} \nabla f(\theta^k) \right) \right\|_2^2 + g(\theta) \right\} \\ & = \underset{\theta \in \mathbb{R}^d}{\operatorname{argmin}} \left\{ \frac{1}{2} \left\| \theta - \left(\theta^k - \frac{1}{L'} \nabla f(\theta^k) \right) \right\|_2^2 + \frac{1}{L'} g(\theta) \right\} \\ & = \underset{\theta \in \mathbb{R}^d}{\operatorname{prox}} \left\{ \frac{1}{2} \left\| \theta - \left(\theta^k - \frac{1}{L'} \nabla f(\theta^k) \right) \right\|_2^2 + \frac{1}{L'} g(\theta) \right\} \end{aligned}$$

The prox operator naturally appears because of the descent lemma

Proximal gradient descent algorithm [also called ISTA]

- Input: starting point θ^0 , Lipschitz constant L > 0 for ∇f
- For $k = 1, 2, \dots$ until *converged* do

•
$$\theta^k = \operatorname{prox}_{g/L} \left(\theta^{k-1} - \frac{1}{L} \nabla f(\theta^{k-1}) \right)$$

• Return last θ^k

Also called **Forward-Backward splitting**. For Lasso with least-squares loss, iteration is

$$\theta^k = S_{\lambda/L} \Big(\theta^{k-1} - \frac{1}{I} (X^\top X \theta^{k-1} - X^\top Y) \Big),$$

where S_{λ} is the soft-thresholding operator

- Put for short F = f + g,
- ullet Take any $heta^* \in \operatorname{argmin}_{ heta \in \mathbb{R}^d} F(heta)$

Theorem (Beck Teboulle (2009))

If the sequence $\{\theta^k\}$ is generated by ISTA, then

$$F(\theta^k) - F(\theta^*) \le \frac{L\|\theta^0 - \theta^*\|_2^2}{2k}$$

- Convergence rate is O(1/k)
- Is it possible to improve the O(1/k) rate?

Yes! Using **Accelerated proximal gradient descent** (called FISTA, Nesterov 83, 04, Beck Teboule 09)

ullet Idea: to find θ^{k+1} , use an interpolation between θ^k and θ^{k-1}

Accelerated proximal gradient descent algorithm [FISTA]

- Input: starting points $z^1 = \theta^0$, Lipschitz constant L > 0 for ∇f , $t_1 = 1$
- For $k = 1, 2, \ldots$ until *converged* do

$$\bullet \ \theta^k = \operatorname{prox}_{g/L}(z^k - \frac{1}{L}\nabla f(z^k))$$

- $t_{k+1} = \frac{1+\sqrt{1+4t_k^2}}{2}$
- $z^{k+1} = \theta_k + \frac{t_k-1}{t_{k+1}} (\theta^k \theta^{k-1})$
- **Return** last θ^k



Theorem (Beck Teboulle (2009))

If the sequence $\{\theta^k\}$ is generated by FISTA, then

$$F(\theta^k) - F(\theta^*) \le \frac{2L\|\theta^0 - \theta^*\|_2^2}{(k+1)^2}$$

- Convergence rate is $O(1/k^2)$
- Is $O(1/k^2)$ the optimal rate in general?

Yes. Put g = 0

Theorem (Nesterov)

For any optimization procedure satisfying

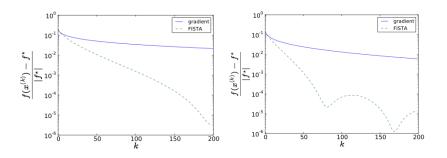
$$\theta^{k+1} \in \theta^1 + \operatorname{span}(\nabla f(\theta^1), \dots, \nabla f(\theta^k)),$$

there is a function f on \mathbb{R}^d convex and L-smooth such that

$$\min_{1 \le j \le k} f(\theta^j) - f(\theta^*) \ge \frac{3L}{32} \frac{\|\theta^1 - \theta^*\|_2^2}{(k+1)^2}$$

for any $1 \le k \le (d-1)/2$.

Comparison of ISTA and FISTA



FISTA is not a descent algorithm, while ISTA is

Backtracking linesearch

What if I don't know L > 0?

- $\bullet \|X^{\top}X\|_{\mathrm{op}}$ can be long to compute
- Letting L evolve along iterations k generally improve convergence speed

Backtracking linesearch. Idea:

- Start from a very small lipschitz constant L
- Between iteration k and k + 1, choose the smallest L satisfying the lemma descent at z^k

Backtracking linesearch

At iteration k of FISTA, we have z^k and a constant L_k

- 2 Do an iteration

$$\theta \leftarrow \operatorname{prox}_{g/L} \left(z^k - \frac{1}{L} \nabla f(z^k) \right)$$

3 Check it this step satisfies the descent lemma at z^k :

$$f(\theta) + g(\theta) \le f(z^k) + \langle \nabla f(z^k), \theta - z^k \rangle + \frac{L}{2} \|\theta - z^k\|_2^2 + g(\theta)$$

- **4** If yes, then $\theta^{k+1} \leftarrow \theta$ and $L_{k+1} \leftarrow L$ and continue FISTA
- **5** It not, then put $L \leftarrow 2L$ (say), and go back to point 2

Sequence L_k is non-decreasing: between iteration k and k+1, a tweak is to *decrease* it a little bit to have (much) faster convergence

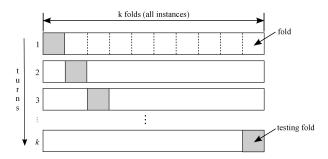
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- Generalization is one the most important goal of machine learning. A trained classifier has to be "generalizable", namely it can be applied in another context than the one of the training dataset, without overfitting
- This can be achieved using cross-validation
- There is no machine learning without cross-validation at some point!
- \bullet We have to choose a penalization parameter λ that generalizes

V-Fold cross-validation

- Most standard cross-validation technique
- Take V=5 or V=10. Pick a random partition I_1,\ldots,I_V of $\{1,\ldots,n\}$, where $|I_v|\approx \frac{n}{V}$ for any $v=1,\ldots,V$



Put

For each $v = 1, \ldots, V$

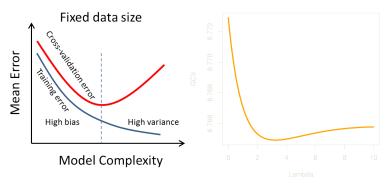
- Put $D_{v,\text{train}} = \bigcup_{v' \neq v} I_{v'}$ and $D_{v,\text{test}} = I_v$
- Find

$$\hat{\theta}_{\nu,\lambda} \in \operatorname*{argmin}_{\theta} \Big\{ \frac{1}{|D_{\nu,\mathtt{train}}|} \sum_{i \in D_{\nu,\mathtt{train}}} \ell(y_i, \langle X_i, \theta \rangle) + \lambda \operatorname{\mathsf{pen}}(\theta) \Big\}$$

Take

$$\hat{\lambda} \in \operatorname*{argmin} \sum_{v=1}^{V} \sum_{i \in D_{v, \text{test}}} \ell(y_i, \langle X_i, \hat{\theta}_{v, \lambda} \rangle)$$



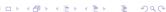


• Training error:

$$\lambda \mapsto \sum_{v=1}^{V} \sum_{i \in D_{v, \text{train}}} \ell(y_i, \langle X_i, \hat{\theta}_{v, \lambda} \rangle)$$

• Testing, validation or cross-validation error:

$$\lambda \mapsto \sum_{v=1}^{V} \sum_{i \in D_{v,v,v}} \ell(y_i, \langle X_i, \hat{\theta}_{v,\lambda} \rangle)$$



- Now I've trained a logistic classifier (or any other classifier), I have an estimation $\hat{\theta}$ of θ
- Or I'm training it but I want to test it as well along my cross-validation loop
- On testing samples (x_i, y_i) , compute (if using logistic classifier)

$$\hat{p}_{i,0} = \mathbb{P}[Y = 0|X = x_i] = \frac{1}{1 + e^{\langle x_i, \hat{\theta} \rangle}},$$

$$\hat{p}_{i,1} = \mathbb{P}[Y = 1|X = x_i] = \frac{1}{1 + e^{-\langle x_i, \hat{\theta} \rangle}}$$

• Predict the label using the MAP rule (Maximum A Posteriori)

$$\hat{y}_i = \arg\max_{y=0,1} \hat{p}_{i,y}$$

• Test it by comparing prediction \hat{y}_i and ground truth y_i

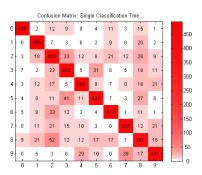


Standard error metrics in classification

Precision, Recall, F-Score, AUC

For each i: true label y_i , predicted label \hat{y}_i

Confusion matrix



		Predicted Class	
		Yes	No
Actual Class	Yes	TP	FN
	No	FP	TN

Precision =
$$\frac{TP}{\#(\text{predicted P})} = \frac{TP}{TP + FP}$$

$$Recall = \frac{TP}{\#(\text{real P})} = \frac{TP}{TP + FN}$$

$$\mathsf{Accuracy} = \frac{\mathsf{TP} + \mathsf{TN}}{\mathsf{TP} + \mathsf{TN} + \mathsf{FP} + \mathsf{FN}} \quad \mathsf{F}\text{-}\mathsf{Score} = 2 \frac{\mathsf{Precision} \times \mathsf{Recall}}{\mathsf{Precision} + \mathsf{Recall}}$$

- In multiclass classification (more than 2 labels), can compute precision and recall for each label
- Recall = Sensitivity
- False-Discovery Rate FDR = 1 Precision
- Many other metrics...

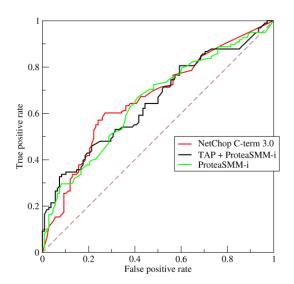
ROC Curve (Receiver Operating Characteristic)

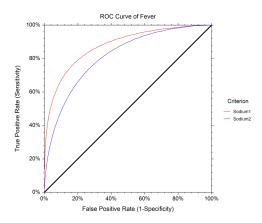
- For binary classification
- True positive Rate TPR = $\frac{TP}{\#(real\ P)} = \frac{TP}{TP+FN}$
- False positive Rate $FPR = \frac{FP}{\#(real\ N)} = \frac{FP}{FP + TN}$
- x-axis: FPR, y-axis: TPR
- Each point A_t of the curve has coordinates (FPR_t, TPR_t), where FPR_t and TPR_t are FPR and TPR of the confusion matrix obtained by the classification rule

$$\hat{y}_i = \mathbf{1}_{\hat{p}_{i,0} \geq t}$$

• AUC score is the Area Under the ROC Curve







Class unbalancing

- In my supervised dataset there are 90% labels 0 and 10% labels 1, but I want to detect 1s
- What if I train without including this in my training rule?
- You'll only predict 0s!

In logistic regression, just correct the likelihood using the class balancing: put

$$\hat{w}_0 = \frac{n}{\{\#i : y_i = 0\}}$$
 and $\hat{w}_1 = \frac{n}{\{\#i : y_i = 1\}}$



Class unbalancing

The logistic goodness-of-fit is

$$R_n(\theta) = \frac{1}{n} \sum_{i=1}^n \left(\log(1 + e^{\langle \theta, x_i \rangle}) \mathbf{1}_{y_i = 1} + \log(1 + e^{-\langle \theta, x_i \rangle}) \mathbf{1}_{y_i = 0} \right)$$

Just replace it by

$$R_n(\theta) = \frac{1}{n} \sum_{i=1}^n \left(\hat{w}_1 \log(1 + e^{\langle \theta, x_i \rangle}) \mathbf{1}_{y_i=1} + \hat{w}_0 \log(1 + e^{-\langle \theta, x_i \rangle}) \mathbf{1}_{y_i=0} \right)$$

- This changes the gradient you use in a solver
- \bullet Gradient steps for 1s are larger then the ones for 0s, when $\#1 \ll \#0$

Class unbalancing

In an unbalanced dataset, when using V-Fold cross-validation,
 I'm likely to end up with a fold without 1s!

Use "stratified" V-Fold cross-validation:

- if there is $p_1\%$ of label 1s in the dataset
- proportion of of 1s must be p_1 % inside each fold
- easy: put 1s in the dataset first, and find fold number of a line using the modulo with the number of folds (see above)

- Features matrix X with *n*-lines and *d*-columns
- ullet $X_{ullet,j}=j$ -th column of X and $X_{j,ullet}=j$ -th row.

Scale of features vector $X_{ullet,1},\dots,X_{ullet,d}$ is important at the training step

- when using penalization, the coefficients of the classifier won't be penalized the same
- Lipschitz constant of the loss often depend on $||X_{\bullet,j}||_2$ (e.g. logistic): features with large scale slow down convergence

Often need to scale the features:

- center, include an intercept, standardize
- min-max scaling
- binarize

On continuous features (continuous is discrete with many modalities...)

• Centering and standardization (or "whitening") of j-th feature: replace $X_{\bullet,j}$ by

$$\frac{X_{\bullet,j} - \bar{X}_{\bullet,j}}{\|X_{\bullet,j} - \bar{X}_{\bullet,j}\|_2}$$

where
$$\bar{X}_{\bullet,j} = \frac{1}{n} \sum_{i=1}^{n} X_{i,j}$$

• Min-max scaling of j-th feature: replace $X_{\bullet,j}$ by

$$\frac{X_{\bullet,j} - \min_i X_{i,j}}{\max_i X_{i,j} - \min_i X_{i,j}}$$

(better for sparse features: keep the zeros)

• Include an intercept: include a constant feature $X_{\bullet,0}=\mathbf{1}$



Feature binarization of *j*-th feature

If $X_{\bullet,j}$ is discrete

• If $X_{i,j} \in \{1, \dots M_j\}$, $M_j =$ number of modalities (small) create $M_j - 1$ new "dummy" binary features: replace

$$\begin{bmatrix} 1 \\ 1 \\ 2 \\ 1 \\ 3 \end{bmatrix} \quad \text{by} \quad \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$

If $X_{\bullet,j}$ is continuous

- Choose number of bins M
- Compute the quantiles $q_{m/M}$ for $m=0,\ldots,M$ of $X_{\bullet,j}$, put $I_m=[q_{(m-1)/M},q_{m/M}]$ for $m=1,\ldots,M$
- ullet Create M-1 dummy binary features $\widetilde{X}_{ullet,j,1},\dots,\widetilde{X}_{ullet,j,M-1}$ such that

$$\widetilde{X}_{i,j,m} = 1$$
 if $X_{i,j} \in I_m$

for
$$m = 1, ..., M - 1$$

Corpus:

```
[ "The lecture about machine learning is really awesome",
  "The teacher is nice and funny. The teacher is a nerd",
  "I'm wondering what I'm going to do with all of this",
  "Maybe create a startup or maybe use these ideas in finance",
  "Maybe I'm just curious about learning things" ]
```

Features:

```
['about', 'all', 'and', 'awesome', 'create', 'curious', 'do',
'finance', 'funny', 'going', 'ideas', 'in', 'is', 'just', 'learning',
'lecture', 'machine', 'maybe', 'nerd', 'nice', 'of', 'or', 'really',
'startup', 'teacher', 'the', 'these', 'things', 'this', 'to', 'use',
'what', 'with', 'wondering']
```

Binarized features:

With many documents and many words, use hashing

Hash function:

set of all possible words
$$\rightarrow \{1, \dots, M\}$$

as much injective as possible. It gives the position of each word in a vector

```
{'and': 26, 'all': 28, 'just': 46, 'awesome': 14, 'startup': 12,
  'learning': 6, 'in': 25, 'curious': 41, 'nerd': 49, 'really': 3,
  'funny': 5, 'use': 10, 'things': 27, 'create': 0, 'ideas': 49,
  'machine': 0, 'to': 37, 'going': 33, 'wondering': 6, 'lecture': 9,
  'is': 12, 'nice': 47, 'do': 21, 'finance': 43, 'what': 20, 'with':
  8, 'teacher': 41, 'about': 12, 'these': 44, 'maybe': 49, 'this': 22,
  'of': 47, 'the': 34, 'or': 17}
```

Standard algorithm: MurmurHash

For scaling word counts ("bag of words"), standard scaling is given by TF-IDF (Time Frequenty - Inverse Document Frequency)

- Reflect how important a word is in a document, relatively to all documents in corpus
- Words w_1, \ldots, w_J , corpus of documents $\mathcal{D} = \{D_1, \ldots, D_I\}$
- Put

$$\mathsf{TF}(w,D) = \# \text{ times } w \text{ occurs in } D$$

$$\mathsf{IDF}(w,\mathcal{D}) = \log \left(\frac{\# \mathcal{D}}{\# \{D \in \mathcal{D} : w \in D\}} \right)$$

Then

$$\mathsf{TF}\mathsf{-}\mathsf{IDF}(w,D,\mathcal{D}) = \mathsf{TF}(w,D) \times \mathsf{IDF}(w,\mathcal{D})$$



Corpus:

```
[ "I like machine learning",
  "I like machine learning a lot",
  "I hate machine learning",
  "I don't understand machine learning",
  "I am an expert of machine learning",
  "My cousin is an expert of machine learning"]
```

Words:

```
['am', 'an', 'cousin', 'don', 'expert', 'hate', 'is', 'learning',
'like', 'lot', 'machine', 'my', 'of', 'understand']
```

TF-IDF:

```
ΓΓ O.
                                         0.43 0. 0. 0. ]
                            0.43 0.79 0.
Γ 0. 0. 0.
                                         0.31 0. 0. 0. 1
               0.
                    0.
                        0.
                            0.31 0.57 0.7
Γ 0. 0. 0.
           0. 0.
                   0.85 0.
                            0.38 0.
                                         0.38 0.
                                                0. 0. 1
Γ0.
    0. 0.
           0.65 0. 0.
                         0. 0.29 0. 0. 0.29 0.
                                                0. 0.65]
[ 0.54 0.44 0.
             0. 0.44 0. 0. 0.24 0.
                                    0. 0.24 0. 0.44 0. ]
Γ0.
   0.35 0.43 0. 0.35 0. 0.43 0.19 0. 0. 0.19 0.43 0.35 0. 11
```

Agenda for tomorrow

- Stochastic Gradient Descent and beyond
- Collaborative Filtering Matrix Completion